Convex optimization in quantum information

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based on joint work with M. Berta (Caltech) & O. Fawzi (ENS Lyon) SIAM J. Opt., 26, 1529 (2016)



Convex optimization and information theory

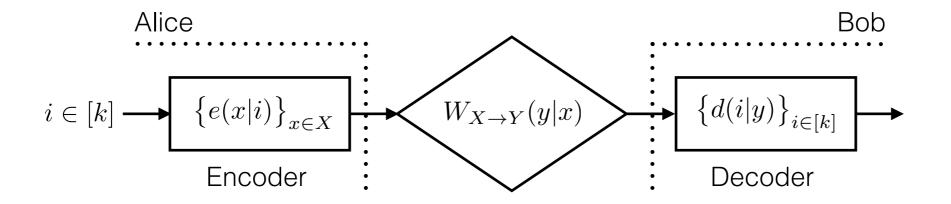
- Many problems in (classical) information theory can be formulated as convex optimization problems
- Examples: Computing capacities, determining good coding schemes, finding upper bounds on errors (to be discussed),...
- There has already been a very fruitful relationship between classical information theory and optimization theory
- Quantum information theory: in very abstract terms, commuting variables have to be replaced by non-commuting variables -> optimization over noncommutative fields
- **This talk**: an introduction into the the subject, based on the problem of sending information over a noisy channel
- In particular, we will focus on constructing relaxations to obtain upper bounds

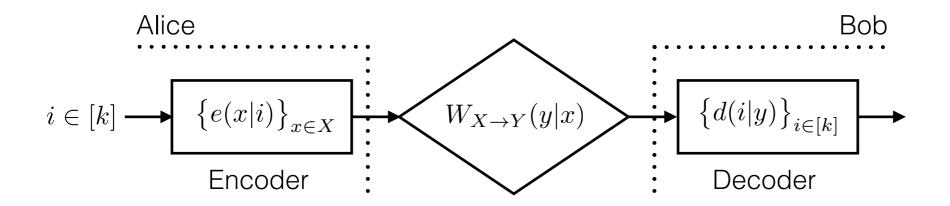
Overview

- Classical noisy channel coding
- Linear program relaxations and the meta-converse
- Entanglement-assisted channel coding (quantum assistance)
- Semidefinite programming (SDPs)
- SDP hierarchies for understanding (bounding) the difference between classical and quantum variables
- Conclusion / Outlook

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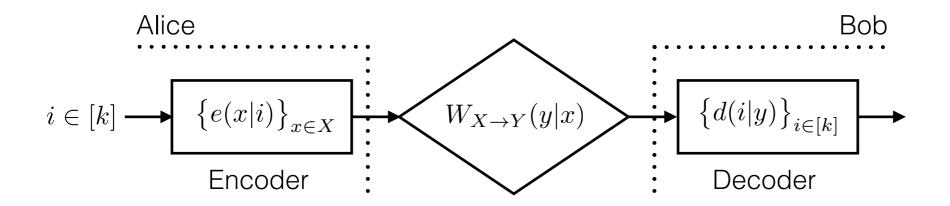
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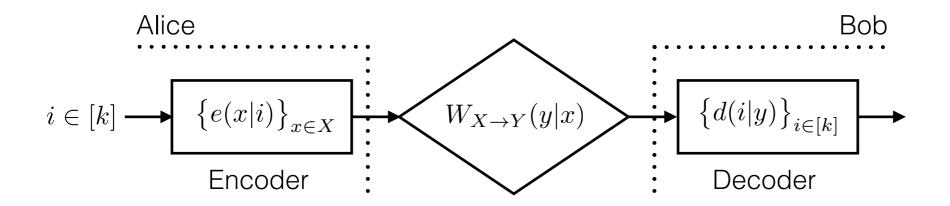
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$$p_{\text{succ}}(W,k) := \underset{(e,d)}{\text{maximize}} \quad \frac{1}{k} \sum_{x,y,i} W_{X \to Y}(y|x) e(x|i) d(i|y) \qquad \text{"bilinear optimisation"}$$

$$\text{subject to} \quad \sum_{x} e(x|i) = 1 \quad \forall i \in [k] \,, \quad \sum_{i} d(i|y) = 1 \quad \forall y \in Y$$

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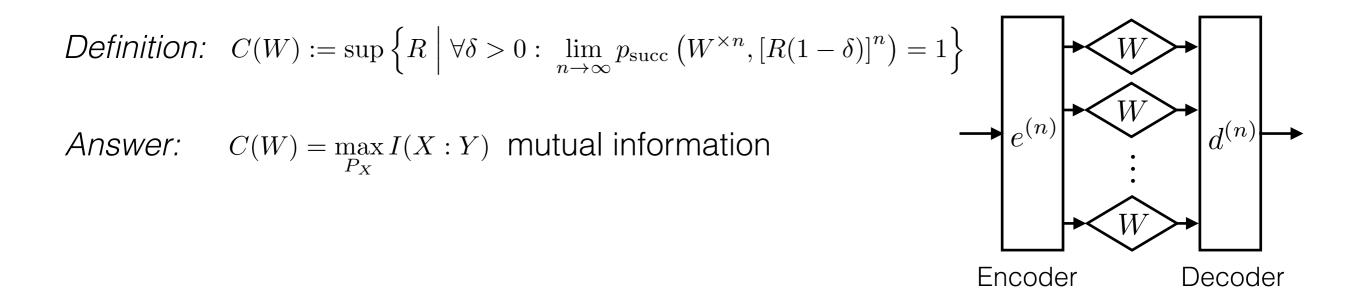
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compared to

Shannon's asymptotic independent and identical distributed (iid) channel capacity:



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idea: consider this quantity as a matrix in x and y variables, and collect all its linear constraints

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 entry-wise positive

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And also:
$$r(x,y) = \sum_i e(x|i)d(i|y) \leq \sum_i e(x|i) = p(x)$$

• The bilinear program can be relaxed to a linear program:

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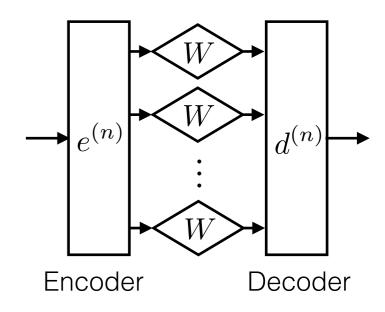
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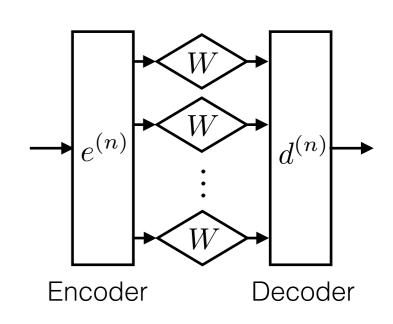
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- This is the meta-converse of Polyanski and Verdu (c.f. Matthews)
- It converges to the exact value of the bilinear optimization program in the limit of many channel uses
- Can be used to obtain very sharp finite n bounds

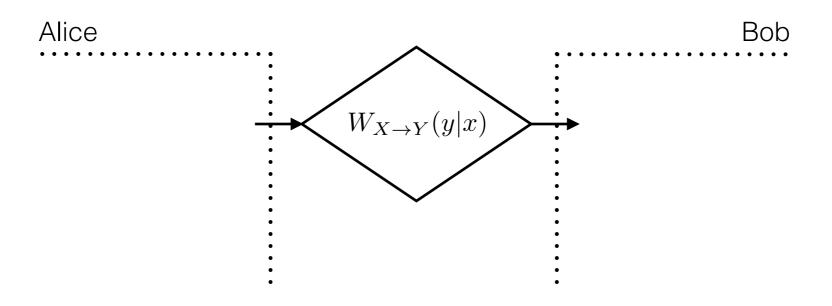


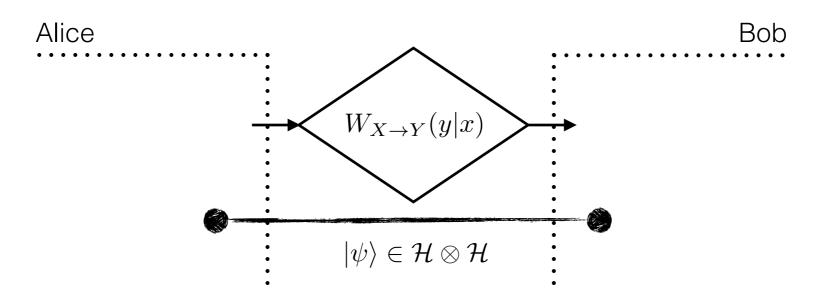
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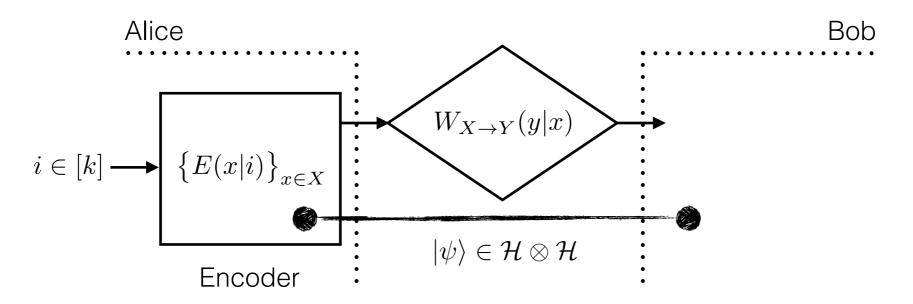
Adding quantum assistance.... but first recap what "quantum" means

- Classical variables are replaced by operators ("matrices") on a Hilbert space ${\cal H}$
- Hilbert space $\mathcal{H}_{}$ = linear vector space equipped with a scalar product (sesquilinear positive definite form)
- Configurations of the physical system are described by elements $|\psi\rangle$ ("states") of unit norm of the Hilbert space
- Separated labaratories are described by taking the tensor product of their respective Hilbert spaces $\mathcal{H}\otimes\mathcal{H}$

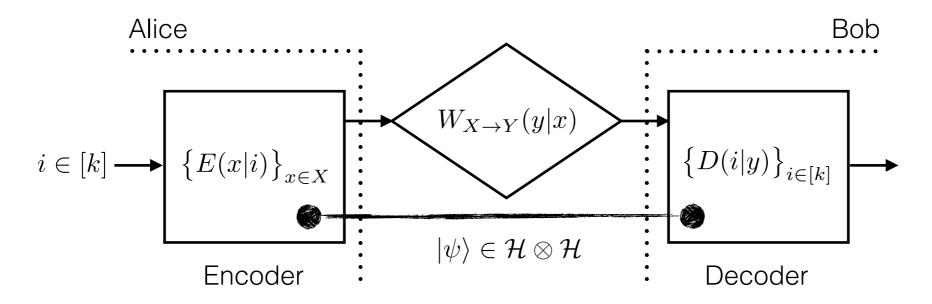




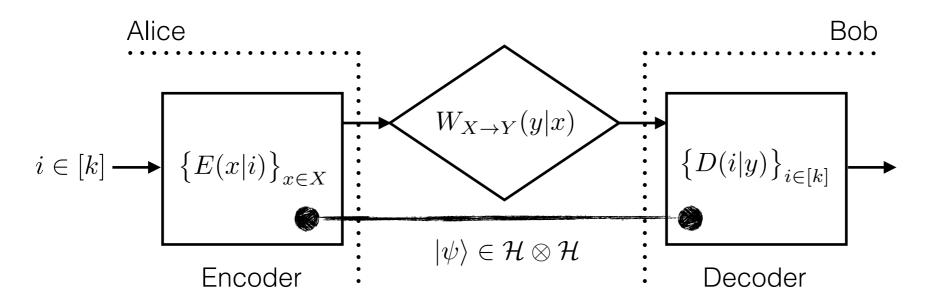
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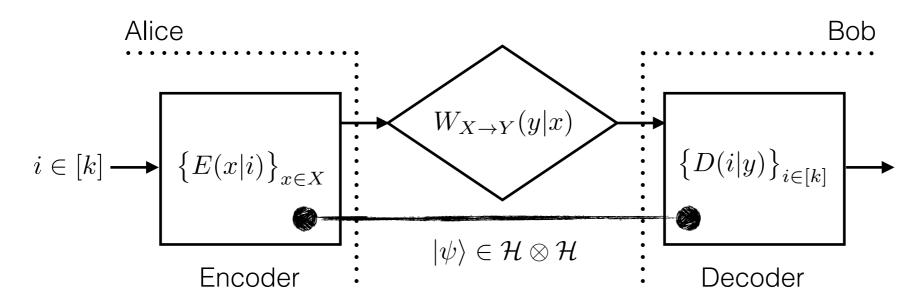
- The encoder and the decoder share an entangled quantum state
- The decoder can also measure his share and combine the outcome with his received output to guess the message
- The encoder can first measure his part of the entangled pair and depending on the or can choose an input into the channel



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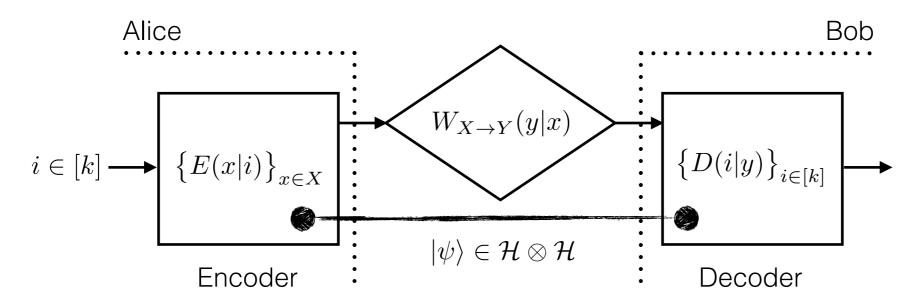
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• Unknown if $p_{\text{succ}}^*(W,k)$ is computable!

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$$p_{\text{succ}}(Z,2) = \frac{5}{6} \approx 0.833 \quad \text{vs.} \quad p_{\text{succ}}^*(Z,2) \ge \frac{2+2^{-1/2}}{3} \approx 0.902$$
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How to obtain upper bounds for the entangled scenario?

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Semi-definite programming (SDPs) (I)

- A semi-definite program (SDP) is a triple (T, A, B) with T a hermitian preserving linear map on matrices, and A, B hermitian matrices
- We can associate to such a triple two optimization programs

$$\begin{array}{lll} \text{maximize} & \operatorname{Trace}[X\,A] & & \min \\ \text{minimize} & \operatorname{Trace}[Y\,B] \\ \text{subject to} & X \geq 0 & \text{subject to} & Y \geq 0 \\ & & T(X) \leq B & & T(X) \geq A \end{array}$$

- Most often, their value agree; this leads to efficient (in terms of the size of the matrices and the approximation error) optimization algorithms
- SDPs can be used to obtain a hierarchy of outer approximations to convex optimization problems (Lassere and Parillo)

Semi-definite programming (SDPs) (II)

- SDPs can be used to obtain a hierarchy of outer approximations to convex optimization problems (Lassere and Parillo)
- Idea: finding a consistent way to construct SDP relaxations of convex optimization problems
- Can be generalized to non-commutative variables (Navascues et. al., Doherty et. al.)
- Our contribution: new converging sequence of tighter SDP relaxations for quantum bilinear optimization problems such as the channel coding problem with entanglement assistance

$$p_{\mathrm{succ}}(W,k) \leq p_{\mathrm{succ}}^*(W,k) = \mathrm{sdp}_{\infty}(W,k) \leq \ldots \leq \mathrm{sdp}_1(W,k)$$
 <— efficiently computable!

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- SDP hierarchies for understanding (bounding) the difference between classical and quantum variables
- Conclusion / Outlook

Quantum bilinear program:

$$p_{\text{succ}}^*(W,k) := \underset{(\mathcal{H},\psi,E,D)}{\text{maximize}} \quad \frac{1}{k} \sum_{x,y,i} W_{X \to Y}(y|x) \langle \psi | E(x|i) \otimes D(i|y) | \psi \rangle$$

$$\text{subject to} \quad \sum_{x} E(x|i) = 1_{\mathcal{H}} \quad \forall i \in [k] \,, \quad \sum_{i} D(i|y) = 1_{\mathcal{H}} \quad \forall y \in Y$$

$$0 \le E(x|i) \le 1_{\mathcal{H}} \, \forall (x,i) \in X \times [k] \,, \quad 0 \le D(i|y) \le 1_{\mathcal{H}} \, \forall (i,y) \in [k] \times Y \,.$$

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$$\text{with} \left[E(x,i), D(y,j) \right] = 0$$

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idea: relaxation of this bilinear form

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motivated by: "NPA hierarchy" (Bell inequalities)

[Lasserre, SIAM (2001)], [Parrilo, Math. Program. (2003)], [Navascues et al., PRL (2007)], [Doherty et al., IEEE CCC (2008)], [Navascues et al., NJP (2008)], [Pironio et al., SIAM (2010)]

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• First step: see as the part of the upper-right block of the Gram matrix

$$\Omega = \sum_{u,v} \langle \psi | X_u X_v | \psi \rangle | u \rangle \langle v | \quad \text{with} \quad X_u = \begin{cases} E(x|i) & u = (i,x) \\ D(j|y) & u = (j,y) \end{cases}$$

$$for i=j$$

$$\Omega = \begin{pmatrix} \frac{\langle \psi | E(x|i) \cdot E(x'|i') | \psi \rangle}{\langle \psi | E(x'|i') \cdot D(y'|j') | \psi \rangle} & \frac{\langle \psi | E(x|i) \cdot D(y|j) | \psi \rangle}{\langle \psi | D(y|j) \cdot D(y'|j') | | \psi \rangle} \end{pmatrix}$$

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• Original constraints can be formulated as positivity conditions on Ω : $sdp_1(W,k)$

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• First level relaxation: $p_{\text{succ}}(W, k) \leq p_{\text{succ}}^*(W, k) \leq \text{sdp}_1(W, k)$

$$\begin{split} \mathrm{sdp}_1(W,k) &= \mathrm{maximize} &\quad \frac{1}{k} \sum_{x,y,i} W_{X \to Y}(y|x) \Omega_{(i,x),(i,y)} \\ \mathrm{subject \ to} &\quad \Omega \in \mathrm{Pos}(1+k|X|+k|Y|) \,, \quad \Omega_{\emptyset,\emptyset} = 1 \quad \mathrm{with} \ \emptyset \ \mathrm{the \ empty \ symbol} \\ &\quad \Omega_{u,v} \geq 0 \quad \forall u,v \in X \times [k] \cup Y \times [k] \cup \{\emptyset\} \\ &\quad \sum_{x} \Omega_{w,(i,x)} = \Omega_{w,\emptyset} \quad \forall i \in [k] \,, w \in X \times [k] \cup Y \times [k] \cup \{\emptyset\} \,. \end{split}$$

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Going back to our example:

$$Z = \begin{pmatrix} 1/3 & 1/3 & 0 & 0\\ 0 & 0 & 1/3 & 1/3\\ 1/3 & 0 & 1/3 & 0\\ 0 & 1/3 & 0 & 1/3\\ 1/3 & 0 & 0 & 1/3\\ 0 & 1/3 & 1/3 & 0 \end{pmatrix}$$

$$p_{
m succ}(Z,2)=rac{5}{6}pprox 0.833$$
 (known before, with two-dimensional assistance) $p_{
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dimensional assistance)

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$$= \begin{pmatrix} 1/3 & 1/3 & 0 & 0 \\ 0 & 0 & 1/3 & 0 \\ 0 & 1/3 & 0 & 0 \\ 0 & 1/3 & 1/3 & 0 \end{pmatrix}$$

$$= \begin{cases} p_{\text{succ}}(Z, 2) = \frac{6}{6} & \text{dimensional assistance} \\ p_{\text{succ}}(Z, 2) \ge \frac{2+2^{-1/2}}{3} \approx 0.902 \\ \text{Relaxation: } p_{\text{succ}}^*(Z, 2) \le \text{sdp}_1(Z, 2) \approx 0.908 = \frac{1}{2} + \frac{1}{\sqrt{6}} \\ \text{Relaxation: } p_{\text{succ}}(Z, 2) \le \text{sdp}_1(Z, 2) \approx 0.908 = \frac{1}{2} + \frac{1}{\sqrt{6}} \\ \text{Tours dimensional assistance} \end{cases}$$

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dimensional assistance)

- Four-dimensional assistance: $p_{\text{succ}}^*(Z,2) \ge \frac{1}{2} + \frac{1}{\sqrt{6}}$

Conclusions

- Fruitful interplay of optimization theory and (quantum) information theory
- Going quantum (= adding quantum assistance to classical tasks) roughly means that commutative variables have to replaced by non-commutative ones
- Optimization becomes harder, but semi-definite programming can be used to obtain converging upper bounds
- Many more directions to explore: fully quantum scenario, other information theoretic protocolls,...

Thanks!